

Vzorek č.	1	2	3	4
Popis	Bez TAST	Zkouška TAST	Referenční bez TAST	5° vlevo
TAST Schedule	-	KROUPA	-	KROUPA
V_compensation enable	-	TRUE	-	TRUE
L_compensation enable	-	TRUE	-	TRUE
V_master current type	-	FEEDBACK	-	FEEDBACK
Sampling timing (no WV)	-	0,5	-	0,5
Comp frame (no WV)	-	TOOL	-	TOOL
V_compensation gain (sensitivity)	-	20/10/30	-	20
V_dead band	-	0	-	0
V_bias rate	-	0	-	0
V_tracking limit	-	600	-	600
V_tracking limit per cycle	-	1	-	1
V_compensation: start count	-	3	-	3
V_master sampling start count	-	2	-	2
V_master sampling count	-	1	-	1
V_master current constant data	-	95	-	95
L_compensation gain (sensitivity)	-	20/10/30	-	20
L_dead band	-	0	-	0
L_bias rate	-	0	-	-10
L_tracking limit	-	600	-	600
L_tracking limit per cycle	-	1	-	1
L_compensation start count	-	3	-	3
Robot Group Mask	-	Default	-	Default
Adjust delay time	-	0,136	-	0,136
V_AG_correction count	-	0	-	0
L_AG_correction count	-	0	-	0
V_AG_correction band	-	4	-	4
L_AG_correction band	-	4	-	4
V_AB_multiplier	-	1,5	-	1,5
L_AG_multiplier	-	1,5	-	1,5
TAST Equip Mask	-	Default	-	Default

Vzorek č.	5	6	7	8
Popis	5° vlevo	5° vlevo	5° vlevo	5° vpravo
TAST Schedule	KROUPA	KROUPA	KROUPA	KROUPA
V_compensation enable	TRUE	TRUE	FALSE	FALSE
L_compensation enable	TRUE	TRUE	TRUE	TRUE
V_master current type	FEEDBACK	FEEDBACK	FEEDBACK	FEEDBACK
Sampling timing (no WV)	0,5	0,5	0,5	0,5
Comp frame (no WV)	TOOL	TOOL	TOOL	TOOL
V_compensation gain (sensitivity)	20	20	-	-
V_dead band	0	0	0	0
V_bias rate	5	10	-	-
V_tracking limit	600	600	600	600
V_tracking limit per cycle	1	1	1	1
V_compensation: start count	3	3	3	3
V_master sampling start count	2	2	2	2
V_master sampling count	1	1	1	1
V_master current constant data	95	95	95	95
L_compensation gain	20	20	20	20
L_dead band	0	0	0	0
L_bias rate	-5	-5	-5	-5/5/10
L_tracking limit	600	600	600	600
L_tracking limit per cycle	1	1	1	1
L_compensation start count	3	3	3	3
Robot Group Mask	Default	Default	Default	Default
Adjust delay time	0,136	0,136	0,136	0,136
V_AG_correction count	0	0	0	0
L_AG_correction count	0	0	0	0
V_AG_correction band	4	4	4	4
L_AG_correction band	4	4	4	4
V_AB_multiplier	1,5	1,5	1,5	1,5
L_AG_multiplier	1,5	1,5	1,5	1,5
TAST Equip Mask	Default	Default	Default	Default

Vzorek č.	9	10	11
Popis	5° vpravo	5° vpravo, 4 mm od středu	5° vpravo, 8 mm od středu
TAST Schedule	KROUPA	KROUPA	KROUPA
V_compensation enable	FLASE	FALSE	FLASE
L_compensation enable	TRUE	TRUE	TRUE
V_master current type	FEEDBACK	FEEDBACK	FEEDBACK
Sampling timing (no WV)	0,5	0,5	0,5
Comp frame (no WV)	TOOL	TOOL	TOOL
V_compensation gain (sensitivity)	-	-	-
V_dead band	0	0	0
V_bias rate	-	-	-
V_tracking limit	600	600	600
V_tracking limit per cycle	1	1	1
V_compensation: start count	3	3	3
V_master sampling start count	2	2	2
V_master sampling count	1	1	1
V_master current constant data	95	95	95
L_compensation gain	20	20	20
L_dead band	0	0	0
L_bias rate	10	10	10
L_tracking limit	600	600	600
L_tracking limit per cycle	1	1	1
L_compensation start count	3	3	3
Robot Group Mask	Default	Default	Default
Adjust delay time	0,136	0,136	0,136
V_AG_correction count	0	0	0
L_AG_correction count	0	0	0
V_AG_correction band	4	4	4
L_AG_correction band	4	4	4
V_AB_multiplier	1,5	1,5	1,5
L_AG_multiplier	1,5	1,5	1,5
TAST Equip Mask	Default	Default	Default