CZECH TECHNICAL UNIVERSITY IN PRAGUE
Faculty of Transportation Sciences
K620 – Department of Transport Telematics
Konviktská 20, 110 00 Prague 1, Czech Republic

SUPERVISOR'S REPORT
ON THE MASTER'S THESIS

Master's thesis title ....
Low-cost implementation of Differential GPS using Arduino

Author (including degrees) .... **Martin Svaton**

Master's thesis supervisor (incl. deg.) .... **Lic. Eng. David Gundlegård**

Evaluation criteria and their classification

Fulfilment of the master's thesis requirements and goals...............A (excellent) ... 1,0

Self-action and own initiative
during the master's thesis elaboration...A (excellent) ... 1,0

Application of knowledge gained
by self-study and from professional literature ....A (excellent) ... 1,0

Usage of groundwork and data from practice ....A (excellent) ... 1,0

Professional level and contribution of the master's thesis ....A (excellent) ... 1,0

Formal aspects of the master's thesis.. C (good) ... 2,0

Further comments to the master's thesis:

Excellent performance in software and hardware development as well as theory related to the thesis.

I **recommend** the master's thesis for the defence.

Summary classification of the master's thesis .... A (excellent) ... 1,0

David Gundlegård
....
master's thesis supervisor´s name

....
master's thesis supervisor´s signature

In September 15, 2016 ....Very- e. g. January 12, 2013 -