CZECH TECHNICAL UNIVERSITY IN PRAGUE



Faculty of Transportation Sciences K620 – Department of Transport Telematics Konviktská 20, 110 00 Prague 1, Czech Republic

SUPERVISOR'S REPORT ON THE MASTER'S THESIS

Master's thesis title	Low cost implementation of Differential GPS using Arduino
Author (including degrees)	Bc. Martin Svatoň
Master's thesis supervisor (incl. deg.)	Ing. Petr Bureš, Ph.D.
	MSc David Gunderlard
Evaluation criteria an	nd their classification
Fulfilment of the master's thesis requirement	nts and goals (excellent) 1,0
Self-action and own initiative during the master's thesis elaboration	A (excellent) 1,0
Application of knowledge gained by self-study and from professional literature	re (excellent) 1,0
Usage of groundwork and data from practic	ce (excellent) 1,0
Professional level and contribution of the m	
Formal aspects of the master's thesis	
Further comments to the master's thesis:	
The goal of the thesis required to understand point of view it required to gather knowledginterfaces, communications, design and createstatistics. This was a considerable scope and Mi	ge ranging from programming services and ation of hardware platform to testing and
I recommend the mast	er's thesis for the defence.
Summary classification of the master's	s thesisA (excellent) 1,0
Petr Bureš	And
master's thesis supervisor's name	master's thesis supervisor's signature
In Prague	20.9. 2016