

I. BASIC INFORMATION

Title:	Noisy non-linear dynamics analysis and control design for the ball levitation set-up
Author:	Ing. Mehdi Badreddine Timizar
Type of thesis:	Master thesis
Faculty:	Faculty of mechanical engineering
Department:	12110 Dept. of Instrumentation and control engineering
Opponent:	Ing. Pavel Trnka
Opponent's workplace:	CTU in Prague, FME, Dept. of Instrumentation and Control Engineering

II. EVALUATION

Difficulty	average

Assignment compliance	satisfied with objections
The 1 st guideline is not satisfied very well. Chapter 1 which should solve this part is poor in terms of both formal and expertise. Other guidelines have been satisfied.	

Procedure of solution	correct

Level of expertise	C - good

Formal and language level, scope of work	E - sufficient
Paper and electronic versions of thesis differ (1 st chapter inserted). The equations are not numbered. Quantities and formulas in 1 st chapter use different formalism opposite to rest of the thesis. Language level is not bad as the author is not a natural speaker, even if some unusual expressions are used. Structure of work is not bad, but chapters are unnumbered and font sizes of headers are confusing. In Chapter 4 volts are signed by lower case letter "v", it should be upper case "V". Scope of thesis (44 pages) is rather small for master thesis.	

Choice of resources, correctness of citations	C - good
Citations are more or less correct. List of sources is correct, but it does not follow citation standard very well.	

Other comments	

III. OVERALL RATING, QUESTIONS FOR THE DEFENSE, PROPOSED CLASSIFICATION

My questions to the author:

Which units are used in the time axes of measured step responses (figures 13 till 20). Is it "seconds" or "samples"?

The main aim – the finding the set-up model and robust controller – is solved, but low quality of thesis combined with average difficulty led me to following classification.

I evaluate the submitted thesis by degree **D - satisfactory**

Date: 28.6.2015

Signature: